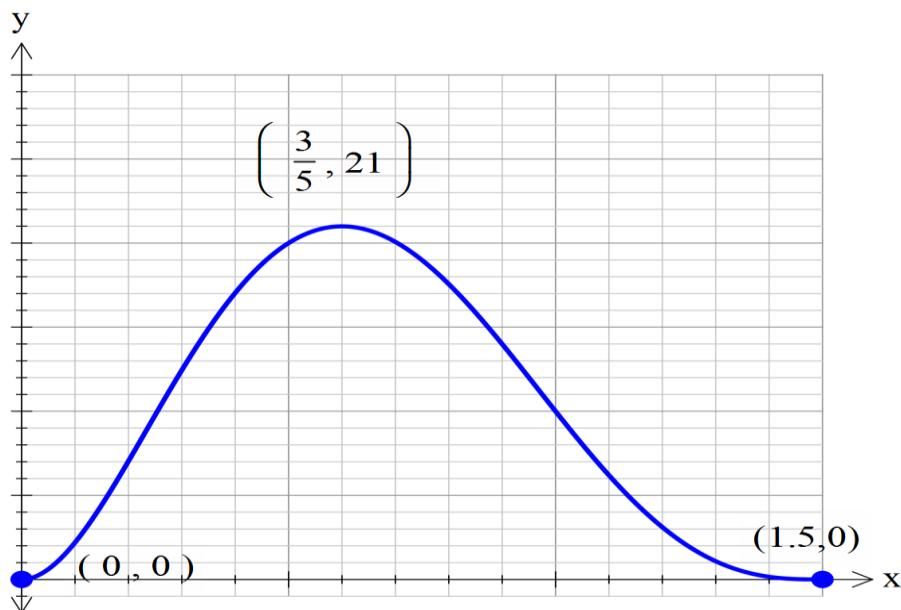


2018 SAC PREP 3 - Solutions

John investigates a path of the form $f(x) = -5px^2(2x - 3)^3, x \in [0, \frac{3}{2}]$.

- a) Sketch a graph of the robot's path when $p = 2$.



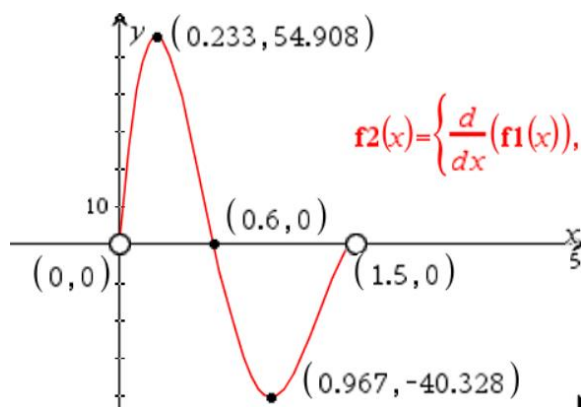
- b) Find the average rate of change between $x = 0$ and $x = 1$.

$$AROC = \frac{f(1) - f(0)}{1 - 0}$$

$$\frac{f(1) - f(0)}{1 - 0}$$

10

- c) Sketch a graph of the derivative function $f'(x)$ when $p = 2$, for a suitable domain. Turning points can be shown to three decimal places. State the domain.



$$f_2(x) = \left\{ \frac{d}{dx} (f_1(x)), \right.$$

Domain $0 < x < \frac{3}{2}$

- d) Find the coordinates, correct to 3 decimal places, of the point on the robot's path where the gradient is the same as the average rate of change found in **part b**).

$$10 = f'(x)$$

$$10 = -20x(2x-3)^2(5x-3)$$

$$x = 0.020 \text{ or } x = 0.550$$

$$(0.020, 0.100) \text{ or } (0.550, 20.745)$$

$$\frac{d}{dx}(f_1(x))$$

$$\left\{ -20 \cdot x \cdot (2 \cdot x - 3)^2 \cdot (5 \cdot x - 3), 0 < x < \frac{3}{2} \right\}$$

$$\text{solve}(-20 \cdot x \cdot (2 \cdot x - 3)^2 \cdot (5 \cdot x - 3) = 10, x)$$

$$x = 0.019658 \text{ or } x = 0.54964$$

$$f_1(x)|_{x=0.019657641277752, 0.5496400390}$$

$$\{ 0.100286, 20.7449 \}$$

- e) Find the angle θ from the positive direction of the x -axis to the tangent to the graph of f at $x=1$, measured in an anti-clockwise direction.

$$f'(1) = -20(1)(2(1)-3)^2(5(1)-3)$$

$$f'(1) = -40$$

$$\theta = \tan^{-1}(-40)$$

$$\theta = 91.43^\circ$$

$$(\tan^{-1}(-40)) \blacktriangleright \text{DD}$$

$$-88.5679038158^\circ$$

$$180 + -88.56790381583$$

$$91.4320961842$$

John wants the robot's path to be smooth and has decided that he wants the angle θ from the positive direction of the x -axis to the tangent to the graph of f to always be less than 75° .

- f) Use a suitable method to determine if when $p = 2$ this requirement is met.

$$\theta = 75^\circ$$

$$m = \tan(75^\circ)$$

$$m = 3.732$$

By considering the graph drawn in part c) we can see that the condition is not met as a maximum gradient of 3.732 is allowed. The gradient of the curve exceeds this value.

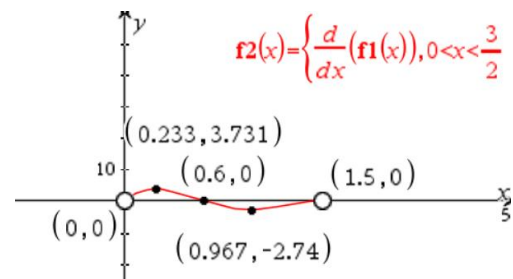
- f) If the condition is not met, determine a suitable value of p that would achieve this requirement.

Maximum gradient is 54.908 we need to dilate this graph by a suitable factor to ensure the gradient is smaller than 3.732.

$$54.908 \times k = 3.73205$$

$$k = 0.068$$

$$p = 0.068 \times 2 = 0.1359(2dp)$$



During some competitions more than one robot can be active in the demonstration area. One of the other robots brushes past John's robot (tangent) when $x = 1$. Return to the curve when $p = 2$

g) Determine the equation of the tangent at this point.

$\frac{d}{dx}(f(x)) _{x=1}$	-40	$f(1) = 10$
$f(1)$	10	$f'(1) = -40$
$\text{solve}(y-10=-40 \cdot (x-1), y)$	$y=50-40 \cdot x$	$y-10 = -40(x-1)$
		$y = 50 - 40x$

If worth one mark: $y = \text{tangentLine}(f(x), x, 1)$ $y = 50 - 40 \cdot x$

h) An out of control robot, travelling in a straight line hits John's robot. Their paths are at right angles to each other. If they collide when $x = 1$, determine the equation of the other robot's path.

$\text{solve}\left(y-10 = \frac{1}{40} \cdot (x-1), y\right)$	$y = \frac{x}{40} + \frac{399}{40}$
$\text{normalLine}(f(x), x, 1)$	$\frac{x}{40} + \frac{399}{40}$

i) Determine the equation of the tangent when $x = a$. Check your result on your CAS.

$$f(a) = -10a^2(2a-3)^3$$

$$f'(a) = -20a(2a-3)^2(5a-3)$$

$$y + 10a^2(2a-3)^3 = -20a(2a-3)^2(5a-3)(x-a)$$

$$y = -20a(2a-3)^2(5a-3)(x-a) - 10a^2(2a-3)^3$$